

Stage LIESSE  
Introduction à l'IA  
A. Apprentissage Supervisé

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# Objectif

Prédire la **classe** (classification) ou la **valeur** (régression) d'un échantillon à partir d'exemples connus.

En pratique, il s'agit d'apprendre une fonction  $f : x \mapsto y$  minimisant:

$$\frac{1}{n} \sum_{i=1}^n \ell(f(x_i), y_i) + \Omega(f)$$

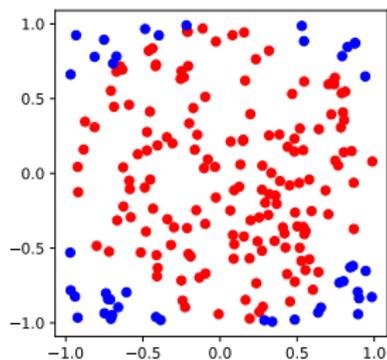
où

- ▶  $x \in \mathbb{R}^d$
- ▶  $y \in \{0, 1\}, \{1, \dots, K\}$  ou  $\mathbb{R}$
- ▶  $(x_1, y_1), \dots, (x_n, y_n)$  sont les données d'apprentissage
- ▶  $\ell$  est la fonction de perte
- ▶  $\Omega$  est une fonction de régularisation (optionnelle)

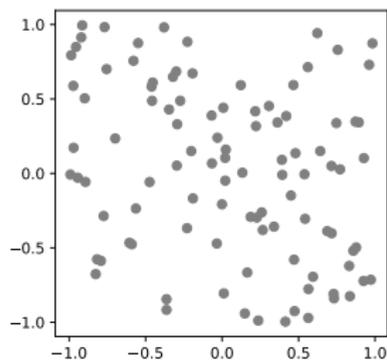
## Exemple (classification)

$$x \in \mathbb{R}^2, y \in \{0, 1\}$$

Données d'entraînement  
( $n = 200$ )



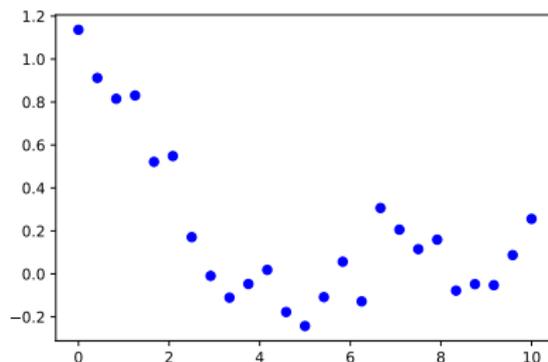
Données de test  
( $n' = 100$ )



# Exemple (régression)

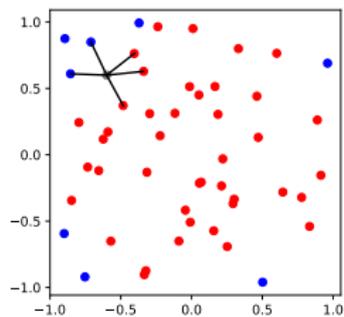
$$x \in \mathbb{R}, y \in \mathbb{R}$$

Données d'entraînement  
( $n = 25$ )

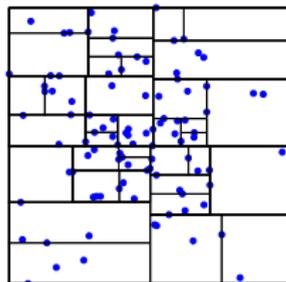


# Plan

## 1. Plus proches voisins



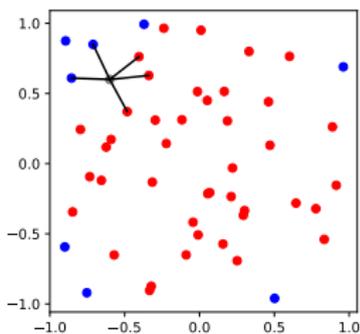
## 2. Recherche arborescente



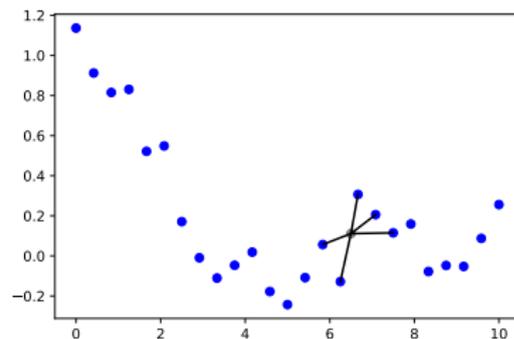
# Algorithme des $k$ plus proches voisins

Une méthode **heuristique**, simple et intuitive.

Classification  
**Vote majoritaire**

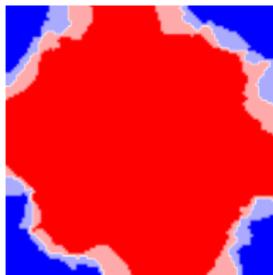


Régression  
**Moyenne**

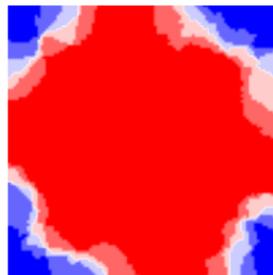


# Exemple en classification

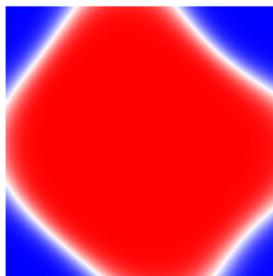
$k = 3$



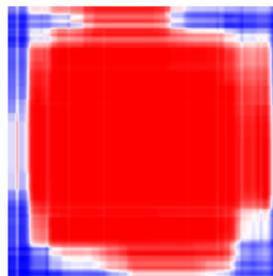
$k = 5$



SVM

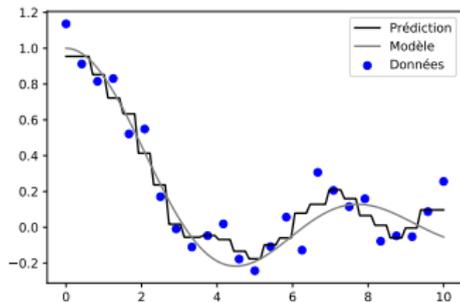


Forêt aléatoire

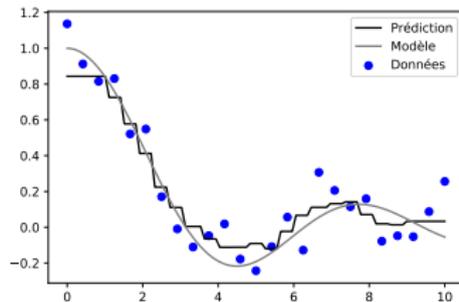


# Exemple en régression

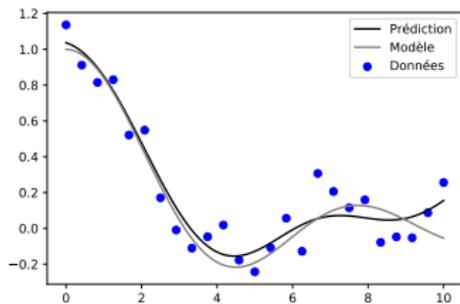
$k = 3$



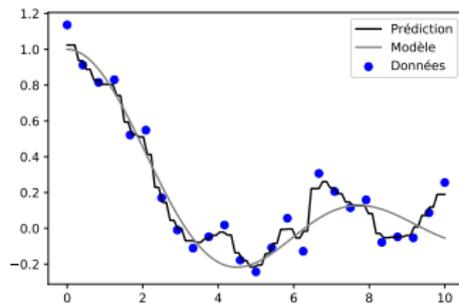
$k = 5$



SVM

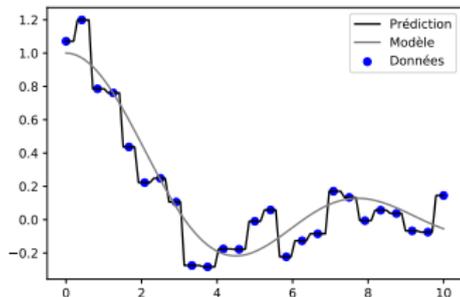


Forêt aléatoire



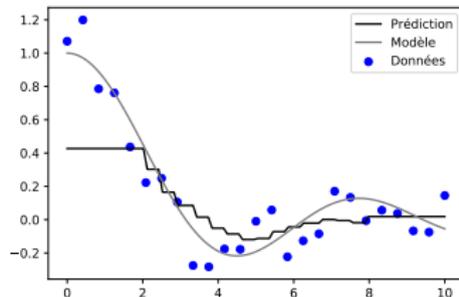
# Dilemne biais-variance

$k = 1$

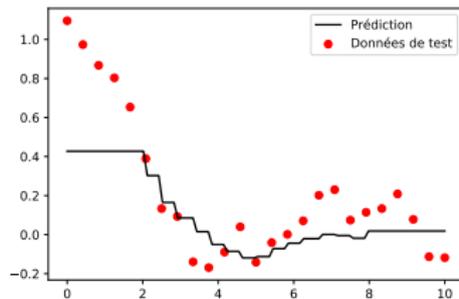
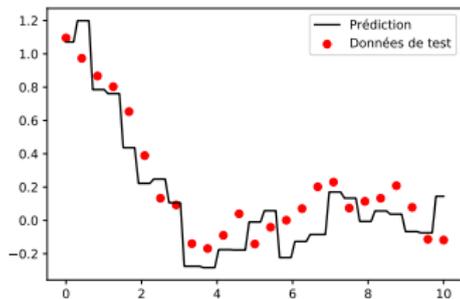


Variance élevée  
**Sur-apprentissage**

$k = 10$

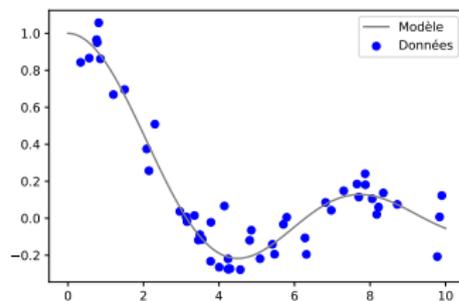
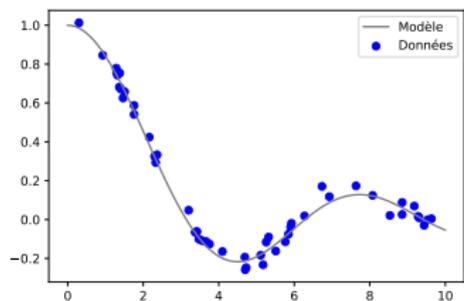


Biais élevé  
**Sous-apprentissage**

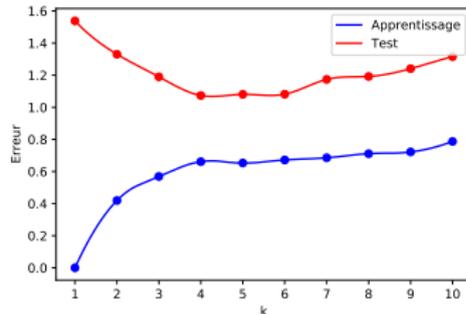
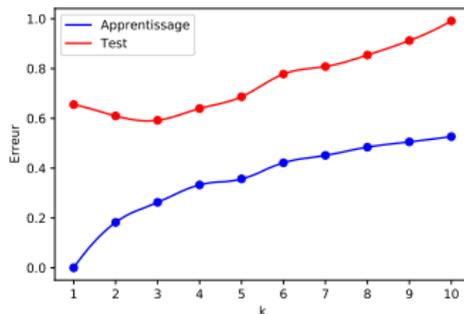


# Quelle valeur de $k$ ?

## Données



## Prédiction



# Application: Digits

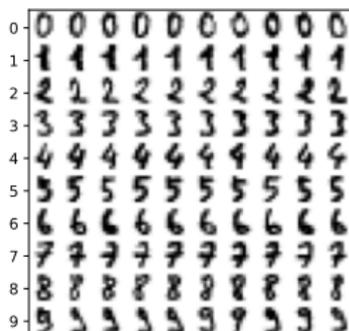
1797 images de chiffres

$8 \times 8$  pixels

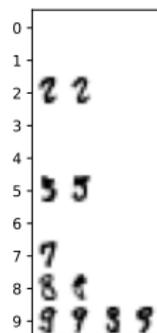
Apprentissage sur 50% des exemples

**Précision = 98%** (pour  $k = 1$ )

Apprentissage

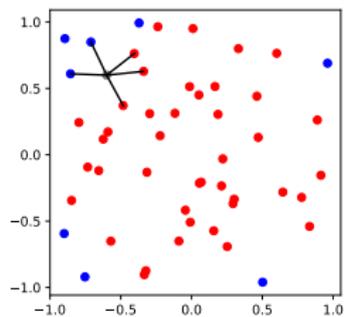


Erreurs sur le test

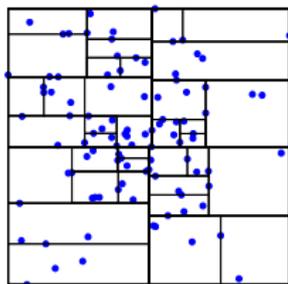


# Plan

## 1. Plus proches voisins



## 2. Recherche arborescente



# Recherche dans un tableau (1D)

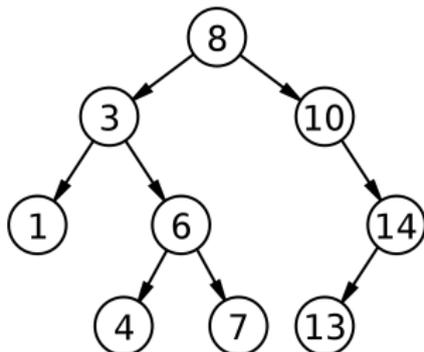
**Données**

8	3	1	6	10	14	4	13	7
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**Requête**

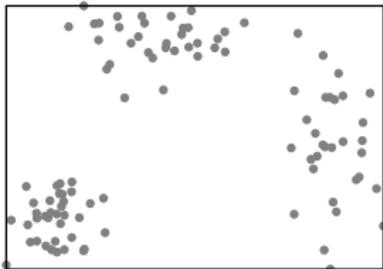
5

**Arbre binaire de recherche**

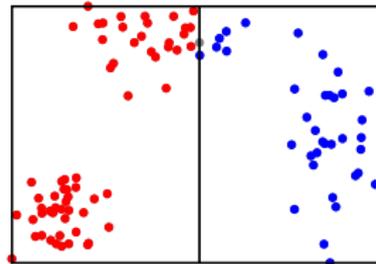


# Arbre k-dimensionnel

**Données**

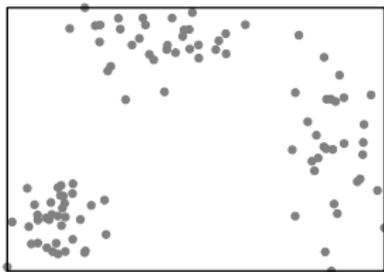


**Première coupe**

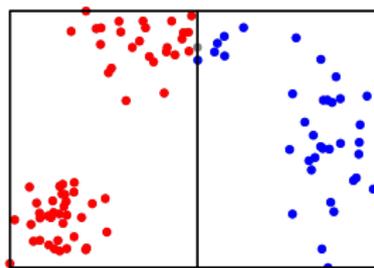


# Arbre k-dimensionnel

Données



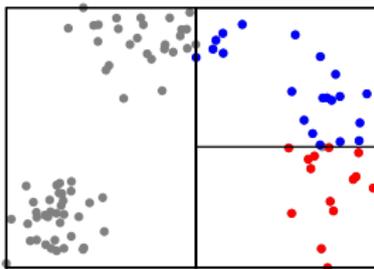
Première coupe



Partition finale



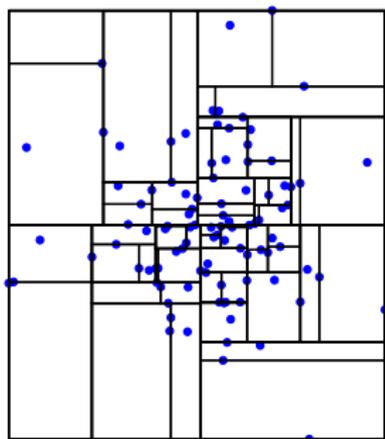
Seconde coupe



# Élagage

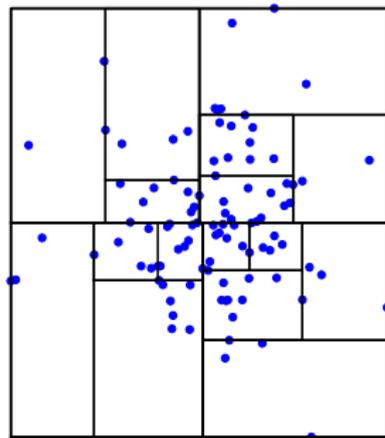
## Arbre complet

Taille des feuilles = 1



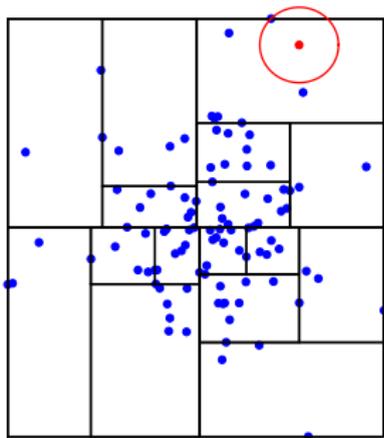
## Arbre élagué

Taille des feuilles  $\leq 10$

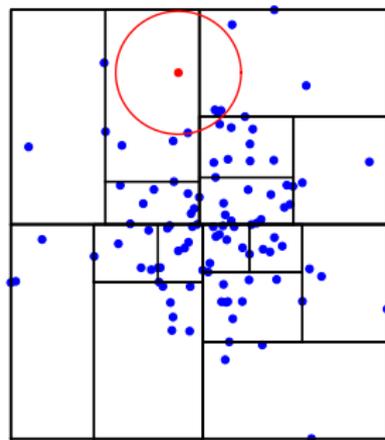


# Recherche dans un arbre k-dimensionnel

**Cas favorable**  
Recherche locale

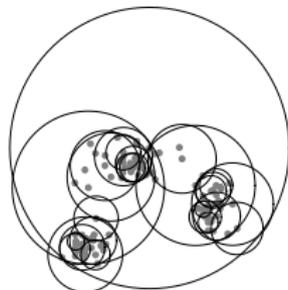
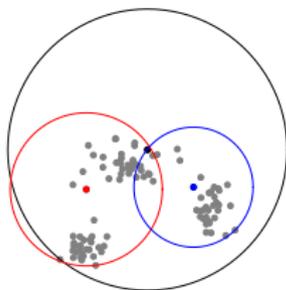
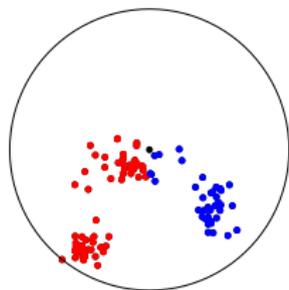


**Cas défavorable**  
Intersection



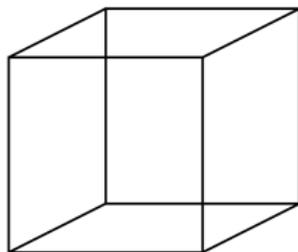
## Arbre boule

Même principe, mais on garde en mémoire la **boule** dans laquelle se trouve chaque partie des données (centre et rayon).



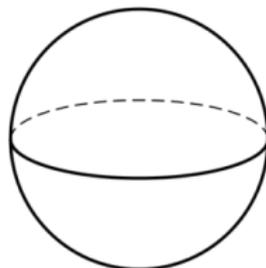
# Compacité

Cube unitaire



$$\text{volume} = 1$$

Boule unitaire



$$\text{volume} = \begin{cases} \frac{\pi^p}{p!} & d = 2p \\ \frac{2^{p+1}\pi^p}{(2p+1)!!} & d = 2p + 1 \end{cases}$$

# Complexité

- ▶ Recherche en  $O(\ln n)$  dans les cas favorables
- ▶ Sensible à la stratégie de coupe (choix de l'axe et du pivot)
- ▶ En pratique, peu efficace en grande dimension ( $d > 20$ )  
→ **fléau de la dimension**

